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APPENDIX A

Finite-Difference Methods

A.1 Forward finite-difference approximation for time derivative

The Taylor series expanded about $u(t)$ is shown in (A-1) - (A-2),

$$u(t + \Delta t) = u(t) + \Delta t \frac{\partial u}{\partial t} + \frac{(\Delta t)^2}{2!} \frac{\partial^2 u}{\partial t^2} + \dots, \quad (\text{A-1})$$

$$\frac{\partial u}{\partial t} = \frac{u(t + \Delta t) - u(t)}{\Delta t} + O(\Delta t). \quad (\text{A-2})$$

The forward difference of $\partial u / \partial t$ at position indices i, j at time index n becomes

$$\left(\frac{\partial u}{\partial t} \right)_{i,j}^n = \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t}. \quad (\text{A-3})$$

A.2 Finite-difference approximation for Laplacian for von Neumann neighborhood

For a function $u(x, y)$, we use the Taylor series about x_i at $(x_i + h)$ and $(x_i - h)$. The expansions are the following,

$$u(x + h, y) = u(x, y) + h \frac{\partial u(x, y)}{\partial x} + \frac{h^2}{2!} \frac{\partial^2 u(x, y)}{\partial x^2} + \frac{h^3}{3!} \frac{\partial^3 u(x, y)}{\partial x^3} + \dots, \quad (\text{A-4})$$

$$u(x - h, y) = u(x, y) - h \frac{\partial u(x, y)}{\partial x} + \frac{h^2}{2!} \frac{\partial^2 u(x, y)}{\partial x^2} - \frac{h^3}{3!} \frac{\partial^3 u(x, y)}{\partial x^3} + \dots \quad (\text{A-5})$$

where h is a grid size, or step size, that is sufficiently small for the second-order approximation to be a good approximation.

Using the subscript notation i, j in x -position and y -position, we can write equations (A-4) and (A-5) as

$$u_{i+1,j} = u_{i,j} + h \frac{\partial u_{i,j}}{\partial x} + \frac{h^2}{2!} \frac{\partial^2 u_{i,j}}{\partial x^2} + \frac{h^3}{3!} \frac{\partial^3 u_{i,j}}{\partial x^3} + \dots, \quad (\text{A-6})$$

$$u_{i-1,j} = u_{i,j} - h \frac{\partial u_{i,j}}{\partial x} + \frac{h^2}{2!} \frac{\partial^2 u_{i,j}}{\partial x^2} - \frac{h^3}{3!} \frac{\partial^3 u_{i,j}}{\partial x^3} + \dots \quad (\text{A-7})$$

If we take (A-6) + (A-7) and rearrange, we get the central difference for the second order derivative with an error $O(h^2)$

$$\frac{\partial^2 u}{\partial x^2} = \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} \quad (\text{A-8})$$

Similarly, for the y -derivative, we obtain

$$\frac{\partial^2 u}{\partial y^2} = \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{k^2} \quad (\text{A-9})$$

Therefore, the approximation of the Laplace equation for a von Neumann neighborhood is the following

$$\begin{aligned} \nabla^2 u(x, y) &= \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \\ &= \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} + \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{k^2} \end{aligned} \quad (\text{A-10})$$

A.3 Finite-difference approximation for Laplacian for Moore neighborhood

For a function $u(x, y)$, we use the Taylor series about x_i and y_j at $(x_i + h, y_j)$, $(x_i - h, y_j)$, $(x_i, y_j + k)$, $(x_i, y_j - k)$, $(x_i + h, y_j + k)$, $(x_i + h, y_j - k)$, $(x_i - h, y_j + k)$ and $(x_i - h, y_j - k)$. The approximation for the first four points is already shown in section A.2 for the von Neumann neighborhood. The expansions for the second four points are as follows:

$$\begin{aligned} u(x + h, y + k) &= u(x, y) + h \frac{\partial u(x, y)}{\partial x} + k \frac{\partial u(x, y)}{\partial y} \\ &+ \frac{1}{2!} \left(h^2 \frac{\partial^2 u(x, y)}{\partial x^2} + 2hk \frac{\partial^2 u(x, y)}{\partial x \partial y} + k^2 \frac{\partial^2 u(x, y)}{\partial y^2} \right) + \dots, \end{aligned} \quad (\text{A-11})$$

$$\begin{aligned} u(x + h, y - k) &= u(x, y) + h \frac{\partial u(x, y)}{\partial x} - k \frac{\partial u(x, y)}{\partial y} \\ &+ \frac{1}{2!} \left(h^2 \frac{\partial^2 u(x, y)}{\partial x^2} - 2hk \frac{\partial^2 u(x, y)}{\partial x \partial y} + k^2 \frac{\partial^2 u(x, y)}{\partial y^2} \right) + \dots, \end{aligned} \quad (\text{A-12})$$

$$\begin{aligned} u(x - h, y + k) &= u(x, y) - h \frac{\partial u(x, y)}{\partial x} + k \frac{\partial u(x, y)}{\partial y} \\ &+ \frac{1}{2!} \left(h^2 \frac{\partial^2 u(x, y)}{\partial x^2} - 2hk \frac{\partial^2 u(x, y)}{\partial x \partial y} + k^2 \frac{\partial^2 u(x, y)}{\partial y^2} \right) + \dots, \end{aligned} \quad (\text{A-13})$$

$$\begin{aligned} u(x - h, y - k) &= u(x, y) - h \frac{\partial u(x, y)}{\partial x} - k \frac{\partial u(x, y)}{\partial y} \\ &+ \frac{1}{2!} \left(h^2 \frac{\partial^2 u(x, y)}{\partial x^2} + 2hk \frac{\partial^2 u(x, y)}{\partial x \partial y} + k^2 \frac{\partial^2 u(x, y)}{\partial y^2} \right) + \dots \end{aligned} \quad (\text{A-14})$$

For a square grid, we assume $x = y = \varepsilon$. Using the two subscript notation i, j in x -position and y -position, we obtain the sum of (A.11) + (A.12) + (A.13) + (A.14) and (A.8) and (A.9), we get the central difference for the second order derivative with an error $O(h^2)$ for the Moore neighborhood as:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{3} \left(\frac{u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} + u_{i+1,j+1} + u_{i+1,j-1} + u_{i-1,j+1} + u_{i-1,j-1} - 8u_{i,j}}{\varepsilon^2} \right) \quad (\text{A-15})$$

Therefore, the approximation of the Laplace equation with Moore neighborhood is the following

$$\begin{aligned} \nabla u^2 &= \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \\ &= \frac{1}{3} \left(\frac{u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} + u_{i+1,j+1} + u_{i+1,j-1} + u_{i-1,j+1} + u_{i-1,j-1} - 8u_{i,j}}{\varepsilon^2} \right) \end{aligned} \quad (\text{A-16})$$

APPENDIX B

Computer Program for Simulation of Discretization
of SIR-PDE Epidemics Model

```

function [Stot,Itot,Rtot] = SIR_FDE(x,y,epsilon,del_t,I_start,alpha,beta,K,tmax)
% approximate SIR_PDE model by finite-difference
% input:      x      : a length of x
%            y      : a length of y
%            epsilon : a grid size
%            del_t   : a step of time
%            I_start : a number of infected
%            alpha   : an infection rate in the same cell
%            beta    : a recovery rate
%            K       : an movement rate
%            tmax    : a max time
% output: Stot      : total number of susceptible individual
%         Itot      : total number of infected individual
%         Rtot      : total number of recovered individual
% size of matrix
row_a = x/epsilon;
col_b = y/epsilon;
% a start cell
start_cell = [row_a/2,col_b/2];
% a start matrix of S, I, R
Sin = ones(row_a,col_b);
Iin = zeros(row_a,col_b);
Rin = zeros(row_a,col_b);
% total number of population
N = Sin+Iin+Rin;
% number of S and I at a start cell
Iin(start_cell(1),start_cell(2)) = I_start;
Sin(start_cell(1),start_cell(2)) = 1-Iin(start_cell(1),start_cell(2));
% start to compute for S, I, R
S0 = Sin;
I0 = Iin;
R0 = N-Sin-Iin;

```

```

DS0 = round(100*S0)/100;
DI0 = round(100*I0)/100;
DR0 = N-S0-I0;
[nrow,ncol] = size(Sin);
irow = 2:nrow-1;
icol = 2:ncol-1;
[IROW,ICOL] = meshgrid(irow,icol);
Stot = zeros(1,tmax);
Itot = zeros(1,tmax);
Rtot = zeros(1,tmax);
k=1;
for n=1:tmax
    interact_S = infect_S(S0);
    interact_I = infect_I(I0);
    interact_R = infect_R(R0);
    if n==1 || 5*fix(n/5)==n
        figure()
        clf reset
        imshow(I0(2:nrow-1,2:ncol-1),'InitialMagnification','fit')
        splot(k) = getframe;
        k=k+1;
    end
% main model
    S01 = ((1-(4*K*del_t/epsilon^2))*S0)+((K*del_t/epsilon^2)*interact_S)-
(alpha*del_t*S0.*I0);
    I01 = ((1-(4*K*del_t/epsilon^2)-
(beta*del_t))*I0)+((K*del_t/epsilon^2)*interact_I)+(alpha*del_t*S0.*I0);
    R01 = ((1-(4*K*del_t/epsilon^2))
*R0)+((K*del_t/epsilon^2)*interact_R)+((beta*del_t)*I0);
% check for value of S, I, R
    S01 = (S01 >= 0).*S01;
    I01 = (I01 >= 0).*I01;

```

```

S0N = (S01 > N).*N;
S0o = (S01 <= N).*S01;
S01 = S0N+S0o;
I0N = (I01 > N).*N;
I0o = (I01<=N).*I01;
I01 = I0N+I0o;
DS0 = S01;
DI0 = I01;
DR0 = N-DS0-DI0;
Stot(n+1) = sum(sum(DS0(irow,icol)));
Itot(n+1) = sum(sum(DI0(irow,icol)));
Rtot(n+1) = sum(sum(DR0(irow,icol)));
S0=S01;
I0=I01;
R0=R01;
end
% plot graph
figure()
movie(splot,1,4);
figure()
plot(2:tmax,Stot(2:tmax),'b-',2:tmax,Itot(2:tmax),'r-',2:tmax,Rtot(2:tmax),'k-');
xlabel('time')
ylabel('population')
legend('Stot','Itot','Rtot',0)
title(sprintf('\n alpha = %0.5g, beta = %0.5g,K= %0.5g',alpha,beta,K));

```

APPENDIX C

Computer Program for Simulation of SIR-CA Epidemics Model

```

function [splot,Stot,Itot,Rtot] =
SIR_CA(row_a,col_b,start_cell,I_start,infec_rate,recover_rate,neighborhood_type,v_
c,v_m,tmax)
% simulate SIR-CA model
% input:      row_a      : number of row
%            col_b      : number of column
%            start_cell  : a start cell
%            I_start     : number of infected at the beginning
%            infec_rate  : an infection rate
%            recover_rate : a recovery rate
%            neighborhood_type : a type of the neighborhood,
%                               1 for von Neumann,
%                               2 for Moore
%            v_c         : connection factor
%            v_m         : movement factor
%            tmax        : a max time
% output:      splot      : simulation of the model
%            Stot        : total number of susceptible individual in the lattice
%            Itot        : total number of infected individual in the lattice
%            Rtot        : total number of recovered individual in the lattice
% check for the neighborhood
if neighborhood_type == 1
    c = [0 v_c 0;v_c 0 v_c;0 v_c 0];
    m = [0 v_m 0;v_m 0 v_m;0 v_m 0];
else
    c = [v_c v_c v_c;v_c 0 v_c;v_c v_c v_c];
    m = [v_m v_m v_m;v_m 0 v_m;v_m v_m v_m];
end
% define the parameters
alpha = infec_rate;
beta = recover_rate;
mu = c.*m.* alpha;

```

```

% define the lattice
Sin = ones(row_a+2,col_b+2);
Iin = zeros(row_a+2,col_b+2);
Rin = zeros(row_a+2,col_b+2);
Iin(start_cell(1)+1,start_cell(2)+1) = I_start;
Sin(start_cell(1)+1,start_cell(2)+1) = 1-Iin(start_cell(1),start_cell(2));
% Total number of people
N = Sin+Iin+Rin;
% Start state of each individual
S0 = Sin;
I0 = Iin;
R0 = N-Sin-Iin;
DS0 = round(100*S0)/100;
DI0 = round(100*I0)/100;
DR0 = N-S0-I0;
[nrow,ncol] = size(Sin);
irow = 2:nrow-1;
icol = 2:ncol-1;
[IROW,ICOL] = meshgrid(irow,icol);
S1=zeros(1,tmax); I1=zeros(1,tmax); R1=zeros(1,tmax);
S1(1) = DS0(start_cell(1)+1,start_cell(2)+1);
I1(1) = DI0(start_cell(1)+1,start_cell(2)+1);
R1(1) = DR0(start_cell(1)+1,start_cell(2)+1);
Stot = zeros(1,tmax); Itot = zeros(1,tmax); Rtot = zeros(1,tmax);
% Compute a value of each state
k=1;
for n=1:tmax
    interact = infect_int(mu,I0,S0);
    if n==1 || 5*fix(n/5)==n
        figure()
        clf reset
        imshow(I0(2:nrow-1,2:ncol-1),'InitialMagnification','fit')

```

```

splot(k) = getframe;
k=k+1;
end
S01 = S0-(alpha *S0.*I0)-interact;
I01 = (1-beta)*I0+(alpha*S0.*I0)+interact;
R01 = R0+(beta*I0);
S01 = (S01 >= 0).*S01;
I01 = (I01 >= 0).*I01;
S0N = (S01 > N).*N;
S0o = (S01 <= N).*S01;
S01 = S0N+S0o;
I0N = (I01 > N).*N;
I0o = (I01 <= N).*I01;
I01 = I0N+I0o;
DS0 = round(100*S01)/100;
DI0 = round(100*I01)/100;
DR0 = N-(DS0+DI0);
S1(n+1) = DS0(26,26);
I1(n+1) = DI0(26,26);
R1(n+1) = DR0(26,26);
Stot(n+1) = sum(sum(DS0(irow,icol)));
Itot(n+1) = sum(sum(DI0(irow,icol)));
Rtot(n+1) = sum(sum(DR0(irow,icol)));
S0=S01; I0=I01; R0=R01;
S01 = S0-(alpha*S0.*I0)-interact;
I01 = (1-beta)*I0+(alpha*S0.*I0)+interact;
R01 = R0+(beta*I0);
S01 = (S01 >=0).*S01;
I01 = (I01 >=0).*I01;
S0N = (S01 > N).*N;
S0o = (S01 <= N).*S01;
S01 = S0N+S0o;

```

```

I0N = (I01 > N).*N;
I0o = (I01 <= N).*I01;
I01 = I0N + I0o;
DS0 = round(100*S01)/100;
DI0 = round(100*I01)/100;
DR0 = N - DS0 - DI0;
S1(n+1) = DS0(start_cell(1)+1, start_cell(2)+1);
I1(n+1) = DI0(start_cell(1)+1, start_cell(2)+1);
R1(n+1) = DR0(start_cell(1)+1, start_cell(2)+1);
Stot(n+1) = sum(sum(DS0(irow,icol)));
Itot(n+1) = sum(sum(DI0(irow,icol)));
Rtot(n+1) = sum(sum(DR0(irow,icol)));
S0=S01; I0=I01; R0=R01;
end
% Plot graph
figure()
movie(splot,1,4);
figure()
plot(1:tmax,S1,'b-',1:tmax,I1,'r-',1:tmax,R1,'k-');
xlabel('time')
ylabel('population')
legend('S1','I1','R1',0)
title(sprintf('\n Start cell with alpha= %0.5g, epsilon = %0.5g',alpha,beta));
figure()
figure()
plot(2:tmax,Stot(2:tmax),'b-',2:tmax,Itot(2:tmax),'r-',2:tmax,Rtot(2:tmax),'k-');
xlabel('time')
ylabel('population')
legend('S','I','R',0)
title(sprintf('\n alpha= %0.5g, beta = %0.5g',alpha,beta));

```

APPENDIX D

Computer Program for Simulation of SIS-CA Epidemics Model

```

function [splot,S1,I1,S2,I2,Stot,Itot] =
SIS_CA(row_a,col_b,start_cell,I_start,v,epsilon,v_c,v_m,neighborhood_type,nmax)
% simulate SIR-CA model
% input:      row_a      : number of row
%            col_b      : number of column
%            start_cell  : a start cell
%            I_start    : number of infected at the beginning
%            v          : an infection rate
%            epsilon    : a recovery rate
%            v_c        : connection factor
%            v_m        : movement factor
%            nmax       : a max time
% output:     splot     : simulation of the model
%            S1         : total number of susceptible individual in a start cell
%            I1         : total number of infected individual in a start cell
%            S2         : total number of susceptible individual in non-start cell
%            I2         : total number of infected individual in non-start cell
%            Stot       : total number of susceptible individual in the lattice
%            Itot       : total number of infected individual in the lattice
% Check for the neighborhood
if neighborhood_type == 1
    c = [0 v_c 0;v_c 0 v_c;0 v_c 0]; m = [0 v_m 0;v_m 0 v_m;0 v_m 0];
else
    c = [v_c v_c v_c;v_c 0 v_c;v_c v_c v_c];
    m = [v_m v_m v_m;v_m 0 v_m;v_m v_m v_m];
end
% Define the parameters
Sin = ones(row_a+2,col_b+2); Iin = zeros(row_a+2,col_b+2);
mu = c.*m.*v;
Iin(start_cell(1),start_cell(2)) = I_start;
Sin(start_cell(1),start_cell(2)) = 1-Iin(start_cell(1),start_cell(2));
% Total number of people

```

```

N=Sin+Iin;
% Start state of each individual
I0 = Iin; S0 = N-Iin; DI0 = round(100*I0)/100; DS0 = N-I0;
[nrow,ncol] = size(Sin);
irow = 2:nrow-1; icol = 2:ncol-1;
[IROW,ICOL] = meshgrid(irow,icol);
S1 = zeros(1,nmax); I1 = zeros(1,nmax); S2 = zeros(1,nmax); I2 = zeros(1,nmax);
S1(1) = DS0(start_cell(1),start_cell(2)); I1(1) = DI0(start_cell(1),start_cell(2));
S2(1) = DS0(start_cell(1)+1,start_cell(2)+1);
I2(1) = DI0(start_cell(1)+1,start_cell(2)+1);
Stot = zeros(1,nmax); Itot = zeros(1,nmax);
% Compute a value of each state
k=1;
for n=1:nmax-1
    interact = infect_int(mu,I0,S0);
    if n==1 || 5*fix(n/5)==n
        figure()
        clf reset
        imshow(I0(2:nrow-1,2:ncol-1),'InitialMagnification','fit')
        splot(k) = getframe; k=k+1;
    end
    I01 = (1-epsilon)*I0+(v*S0.*I0)+interact;
    S01 = N-I01; S01 = (S01 >=0).*S01; I01 = (I01>=0).*I01;
    S0N = (S01 > N).*N; S0o = (S01<=N).*S01;
    S01 = S0N+S0o; I0N = (I01 > N).*N;
    I0o = (I01<=N).*I01; I01 = I0N+I0o;
    DI0 = round(100*I01)/100; DS0 = N-DI0;
    S1(n+1) = DS0(26,26); I1(n+1) = DI0(26,26);
    S2(n+1) = DS0(27,27); I2(n+1) = DI0(27,27);
    Stot(n+1) = sum(sum(DS0(irow,icol))); Itot(n+1) = sum(sum(DI0(irow,icol)));
    S0=S01; I0=I01;
end

```

```

% Plot graph
figure()
movie(splot,2,4);
figure()
plot(1:nmax,S1,'b-',1:nmax,I1,'r-');
xlabel('time')
ylabel('population')
legend('S','I',0)
title(sprintf('\n Start cell with alpha= %0.5g, beta= %0.5g',v,epsilon));
figure()
plot(1:nmax,S2,'b-',1:nmax,I2,'r-');
xlabel('time')
ylabel('population')
legend('S','I',0)
title(sprintf('\n Non-start cell with alpha= %0.5g, beta= %0.5g',v,epsilon));
if neighborhood_type == 1
figure()
plot(2:nmax,Stot(2:nmax),'b-',2:nmax,Itot(2:nmax),'r-');
xlabel('time')
ylabel('population')
legend('S','I',0)
title(sprintf('\n von Neumann neighborhood with alpha= %0.5g, beta=
%0.5g',v,epsilon));
else
figure()
plot(2:nmax,Stot(2:nmax),'b-',2:nmax,Itot(2:nmax),'r-');
xlabel('time')
ylabel('population')
legend('S','I',0)
title(sprintf('\n Moore neighborhood with alpha= %0.5g, beta= %0.5g',v,epsilon));
end

```

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