

เอกสารอ้างอิง

1. Sojourner Rover Home Page. [online] 1997. [cited June 1, 2005]. Available from : URL : <http://mars.jpl.nasa.gov/MPF/rover/sojourner.html>
2. Didier Papadopoulos. “Stable Running for A Quadruped Robot with Compliant Legs.” Master Thesis, Department of Mechanical Engineering, McGill University, 2000.
3. A. Banos, M. A. Jimenez, P. Gonzales de Santos and M. A. Armada. “A massless leg dynamic model for the RIMHO walking machine.” 23rd international Symposium on Industrial Robots, 6 - 9 october, Barcelona, Spain, 1992.
4. P. Kulvanit and S. Laowattana. “Critical Issues for Biped Mechanism in achieving Dynamically Stable Legged Locomotion.” the Proceeding of 17th Mechanical Engineering Conference, October 15-17, 2003.
5. Boonserm Kijisirikul. Artificial Intelligence. [online] 2003. [cited June 1, 2005]. Available from : URL : <http://zeus.cp.eng.chula.ac.th/~boonserm/teaching/ai1.0.2.pdf>
6. Jones M. Tim. AI application programming. Massachusetts: Charls river media, inc, c2003.
7. Haykin, S. Neural Network: A comprehensive foundation. New York, NY: Macmillan, c1994.
8. Russell Smith. Open Dynamics Engine v0.5 User Guide. [online] 2006. [cited June 1, 2006] Available from : URL : <http://ode.org/ode-latest-userguide.html>
9. Parallax Servo Controller. [online] 2005. [cited June 1, 2005]. Available from : URL : http://www.parallax.com/dl/docs/prod/motors/ServoControllerManualRevBv2_4.pdf
10. Olivier Michel. “WebotsTM: Professional Mobile Robot Simulation.” International Journal of Advanced Robotic Systems, 2004, pp. 39-42.
11. Honglak Lee, Yirong Chen, Chih-Han Yu, Gurjeet Singh and Andrew Y. Ng. “Quadruped Robot Obstacle Negotiation via Reinforcement Learning.” Proceedings of the 2006 IEEE International Conference on Robotics and Automation, Orlando, Florida 2006.
12. Gary B. Parker and Zhiyi Li. “Evolving Neural Networks for Hexapod Leg Controller.” Proceedings of the 2003 IEEE/RSJ intl Conference on Intelligent Robots and Systems, Las Vegas, Nevada October 2003, pp. 1376 – 1381.

13. Arndt von Twickel. "Obstacle perception by scorpions and robots From biology to robotics via physical simulation and evolving neural networks." Diploma Thesis, Faculty of Mathematics and Science, University of Bonn, 2004.
14. Z. Zhang, Y. Fukuoka, and H. Kimura. "Adaptive running of a quadruped robot on irregular terrain based on biological concepts." in International Conference on Robotics and Automation, 2003, pp. 2043–2048.
15. Gordon Wych and Gregg Buskey. "Flight Control Using an Artificial Neural Network." Proceedings of the Australian Conference on Robotics and Automation (ACRA 2000), August 30 - September 1, 2000, Melbourne, pp. 65 -70.