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Thesis Title : Digital Speed and Torque Control System of
D.C.Motor Without Current Feedback.
Concentration : Electrical Engineering
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Abstract

The thesis reports a digital speed and torque control system of a D.C. motor without current feedback. The technique, employed in this study, is similar to well-known analog control. However, in the current control loop, the current feedback signal is derived from the motor speed obtained from the encoder. This signal is used for comparison with the current reference. A personal computer 286 is used as PID controllers both in the current loop and speed loop.

An optimum operating conditions are determined by amount optimum and symmetrical optimum criteria.

The system is tested with a phase controlled D.C. converter, which supplying a 10 KW D.C. motor. The experimental results show that, although the sampling period from PC is rather long (55 ms) it is sufficient for controlling d.c. motor which has a rather long mechanical time constant. Transient response of the calculated current is always a lot less than the measured current (about 50%). This might be the result of the time delay occurs in calculation. The steady state response of the calculated current agree well with the measured current.

Comparison with the analog control shows that this method causes higher percentage of ripple in the steady state current. However, there is no obvious difference in the speed response both dynamically and statically.