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## **APPENDICES**

## APPENDIX A

## Notations

$(\Omega, \mathcal{F}, P)$	Probability space
$\Omega$	Outcome space
$\mathcal{F}$	$\sigma$ -field
$P$	Probability measure
$\sigma(X)$	$\sigma$ -field generated by random variable $X$
$(X \in B)$	$\{\omega \in \Omega : X(\omega) \in B\}$
$(X \leq x)$	$\{\omega \in \Omega : X(\omega) \leq x\}$
$E[X]$	Expectation of the random variable $X$
$I_A$	Indicator of set $A$
$\mathbb{N}$	Set of positive integers
$\mathbb{R}$	Real line
$\max$	Maximum
$\min$	Minimum

## APPENDIX B

### Probability Theory

We recall some definition and theorem in probability theory. Most of these results can be found in Brzeźniak and Zastawniak (1999), Capiński and Kopp (2004), and Aggoun and Elliott (2004).

**Definition B.1** Let  $\Omega$  be a non-empty set. A  $\sigma$ -field  $\mathcal{F}$  on  $\Omega$  is a family of a subsets of  $\Omega$  such that

1. the empty set  $\emptyset$  belong to  $\mathcal{F}$ ;
2. if  $A$  belong to  $\mathcal{F}$ , then so does the complement  $\Omega \setminus A$ ;
3. if  $A_1, A_2, \dots$  is a sequence of sets in  $\mathcal{F}$ , then their union  $A_1 \cup A_2 \cup \dots$  also belong to  $\mathcal{F}$ .

**Definition B.2** Let  $\mathcal{F}$  be a  $\sigma$ -field on  $\Omega$ . A *probability measure*  $P$  is a function

$$P : \mathcal{F} \rightarrow [0, 1]$$

such that

1.  $P(\Omega) = 1$ ;
2. if  $A_1, A_2, \dots$  are pairwise disjoint set (that is,  $A_i \cap A_j = \emptyset$  for  $i \neq j$ ) belong to  $\mathcal{F}$ , then

$$P(A_1 \cup A_2 \cup \dots) = P(A_1) + P(A_2) + \dots$$

The triple  $(\Omega, \mathcal{F}, P)$  is called a *probability space*. The sets belonging to  $\mathcal{F}$  is called *events*. An event  $A$  is said to occur *almost surely* (a.s.) whenever  $P(A) = 1$ .

**Definition B.3** If  $\mathcal{F}$  is a  $\sigma$ -field on  $\Omega$ , then a function  $X : \Omega \rightarrow \mathbb{R}$  is said to be  $\mathcal{F}$ -*measurable* if

$$(X \in B) := \{\omega \in \Omega : X(\omega) \in B\} = X^{-1}(B) \in \mathcal{F}$$

for every Borel set  $B \in \mathcal{B}(\mathbb{R})$ . If  $(\Omega, \mathcal{F}, P)$  is a probability space, then such a function  $X$  is called a *random variable*.

**Definition B.4** The  $\sigma$ -field  $\sigma(X)$  generated by a random variable  $X : \Omega \rightarrow \mathbb{R}$  consists of all sets of the form  $(X \in B)$ , where  $B$  is a Borel set in  $\mathbb{R}$ .

**Lemma B.1 (Doob-Dynkin)** Let  $X$  be a random variable. Then each  $\sigma(X)$ -measurable random variable  $Y$  can be written as

$$Y = f(X)$$

for some Borel function  $f : \mathbb{R} \rightarrow \mathbb{R}$ .

**Definition B.5** Every random variable  $X : \Omega \rightarrow \mathbb{R}$  gives rise to a probability measure

$$P_X(B) = P(X \in B)$$

on  $\mathbb{R}$  defined on the  $\sigma$ -field of Borel sets  $B \in \mathcal{B}(\mathbb{R})$ . We call  $P_X$  the distribution of  $X$ . The function  $F_X : \mathbb{R} \rightarrow [0, 1]$  defined by

$$F_X(x) = P(X \leq x)$$

is called the *distribution function* of  $X$ .

**Definition B.6** If there is a Borel function  $f_X : \mathbb{R} \rightarrow \mathbb{R}$  such that for any Borel set  $B \subset \mathbb{R}$

$$P(X \in B) = \int_B f_X(x) dx$$

then  $X$  is said to be a random variable with *absolutely continuous distribution* and  $f_X$  is called *density* of  $X$ . If there is a (finite or infinite) sequence of pairwise distinct real numbers  $x_1, x_2, \dots$  such that for any Borel set  $B \subset \mathbb{R}$

$$P(X \in B) = \sum_{x_i \in B} P(X = x_i),$$

then  $X$  is said to have *discrete distribution* with value  $x_1, x_2, \dots$  and *mass*  $P(X = x_i)$  at  $x_i$ .

**Definition B.7** A random variable  $X : \Omega \rightarrow \mathbb{R}$  is said to be *integrable* if

$$\int_{\Omega} |X| dP < \infty.$$

Then

$$E[X] := \int_{\Omega} X dP$$

exists and is called the *expectation* of  $X$ .

**Definition B.8** Two events  $A, B \in \mathcal{F}$  are called *independent* if

$$P(A \cap B) = P(A)P(B).$$

In general, we say that  $n$  events  $A_1, A_2, \dots, A_n \in \mathcal{F}$  are *independent* if

$$P(A_{i_1} \cap A_{i_2} \cap \dots \cap A_{i_k}) = P(A_{i_1})P(A_{i_2}) \dots P(A_{i_k})$$

for any indices  $1 \leq i_1 < i_2 < \dots < i_k \leq n$ .

**Definition B.9** Two random variable  $X$  and  $Y$  are called *independent* if for any Borel sets  $A, B \in \mathcal{B}(\mathbb{R})$  the two events

$$(X \in A) \text{ and } (Y \in B)$$

are independent. We say that  $n$  random variable  $X_1, X_2, \dots, X_n$  are *independent* if for any Borel sets  $B_1, B_2, \dots, B_n \in \mathcal{B}(\mathbb{R})$  the events

$$(X_1 \in B_1), (X_2 \in B_2), \dots, (X_n \in B_n)$$

are independent.

**Definition B.10** Two  $\sigma$ -fields  $\mathcal{G}$  and  $\mathcal{H}$  contain in  $\mathcal{F}$  are called *independent* if any two events  $A \in \mathcal{G}$  and  $B \in \mathcal{H}$  are independent. Similarly, any finite number of  $\sigma$ -fields  $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_n$  contained in  $\mathcal{F}$  are *independent* if any  $n$  events

$$A_1 \in \mathcal{G}_1, A_2 \in \mathcal{G}_2, \dots, A_n \in \mathcal{G}_n$$

are independent.

**Definition B.11** We say that a random variable  $X$  is *independent* of  $\sigma$ -field  $\mathcal{G}$  if the  $\sigma$ -fields  $\sigma(X)$  and  $\mathcal{G}$  are independent.

**Definition B.12** A *Stochastic process* is a family of random variable  $X(t)$  parametrized by  $t \in T$ , where  $T \subset \mathbb{N}$ . When  $T = \mathbb{N}$ , we shall say that  $X(t)$  is a stochastic process in *discrete time* (i.e., a sequence of random variable). When  $T$  is an interval in  $\mathbb{R}$  (typically  $T = [0, \infty)$ ), we shall say that  $X(t)$  is a stochastic process in *continuous time*.

**Theorem B.2 (Lebesgue's Dominated Convergence Theorem)** Suppose  $\{X_n, n \in \mathbb{N}\}$  is a sequence of random variables such that  $|X_n| \leq Y$  a.s. where  $Y$  is an integrable random variable. If  $X_n$  converges to  $X$  a.s., then  $X_n$  and  $X$  are integrable,

$$\lim_{n \rightarrow \infty} \int_{\Omega} X_n dP = \lim_{n \rightarrow \infty} \int_{\Omega} X dP$$

and

$$\lim_{n \rightarrow \infty} \int_{\Omega} |X_n - X| dP = 0.$$

**Theorem B.3** Let  $(\Omega, \mathcal{F}, P)$  be a probability space. Given a random variable  $X : \Omega \rightarrow \mathbb{R}$ ,

$$\int_{\Omega} g(X(\omega)) dP(\omega) = \int_{\mathbb{R}} g(x) dP_X(x).$$

**Theorem B.4** If  $P_X$  defined on  $\mathbb{R}^n$  is absolutely continuous with density  $f_X$ ,  $g : \mathbb{R}^n \rightarrow \mathbb{R}$  is integrable with respect to  $P_X$ , then

$$\int_{\mathbb{R}^n} g(x) dP_X(x) = \int_{\mathbb{R}^n} f_X(x) g(x) dx.$$

**Corollary B.5** In the situation of the previous theorem we have

$$\int_{\Omega} g(X) dP = \int_{\mathbb{R}^n} f_X(x) g(x) dx.$$

**Theorem B.6** Let  $(\Omega, \mathcal{F}, P)$  be a probability space. Let  $X$  be a real random variable and  $B$  a Borel set. Then

$$\int_B g(x) dF_X(x) = \int_{X^{-1}(B)} g(X(\omega)) dP(\omega).$$

Here  $g$  is a Borel function and where  $B = \mathbb{R}$

$$\int_{\mathbb{R}} g(x) dF_X(x) = \int_{\Omega} g(X(\omega)) dP(\omega).$$

**Proposition B.7** Let  $(\Omega, \mathcal{F}, P)$  be a probability space.

- (i)  $F_X$  is non-decreasing ( $y_1 \leq y_2$  implies  $F_X(y_1) \leq F_X(y_2)$ );
- (ii)  $\lim_{y \rightarrow \infty} F_X(y) = 1$ ,  $\lim_{y \rightarrow -\infty} F_X(y) = 0$ ;
- (iii)  $F_X$  is right continuous (if  $y \rightarrow y_0$ ,  $y \geq y_0$ , then  $F_X(y) \rightarrow F_X(y_0)$ ).

## APPENDIX C

### Computer Programs

This appendix contains a copy of the program written in **MatLab** to implement the approximation in chapter III.

Here we choose parameters;  $u = 0$ ,  $p = 0.5$ ,  $\lambda = 1.0$  and  $\theta = 0.1$  (i.e.,  $c_0 = 1.1$ ). In the following code,  $u$ ,  $c_0$  and  $\lambda$  is represented by  $s$ ,  $c$  and  $\lambda$ , respectively.

————— Table 3.1 in Chapter III —————

```

clc; clear;
% Set the parameters
s=0; p=0.5; c=1.1; lambda=1;
R=[ ];

% Ruin probabilities of the first and second times
R(1) = p*exp(-lambda*(s+c));
R(2) = p*exp(-lambda*(s+2*c))*(exp(lambda*c)+(1-p)+lambda*p*(s+c));
syms u
f = exp(lambda*c)+(1-p)+lambda*p*(u+c)
% Ruin probabilities for n = 3 to 82
for n = 3:82
    f0 = f;
    f00 = (1-p)*subs(f0,u,'u+c') + lambda*p*int(f0,u,[0],[u+c]);
    f = exp((n-1)*lamda*c) + f00;
    g = p*exp(-lambda*(u+c)) + p*exp(-lambda*n*c-lambda*u)*f00;
    T = subs(g,u,'0');
    T = subs(T);
    n
    R(n) = T
end

```

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